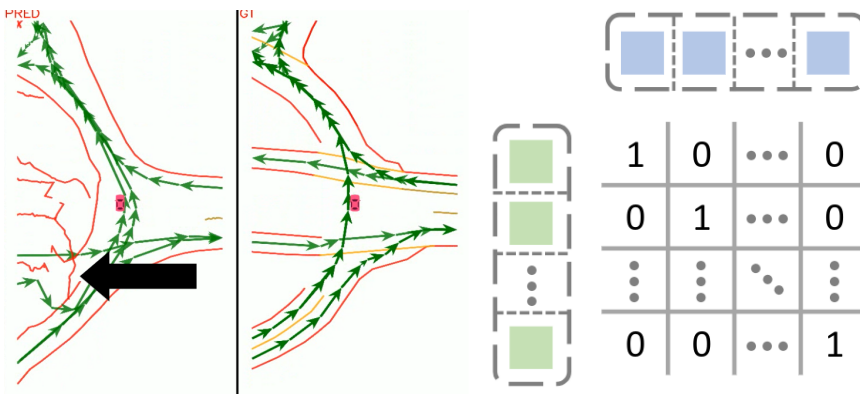


Bachelor Thesis / Master Thesis



Logical Error in the Prediction of a Model (left), Example Visualization of Consistency Checks (right)

Logical Consistency for Birds-Eye-View Road Feature Perception with Deep Learning

The field of map perception, meaning the detection of road features like road borders, lane dividers and lane centerlines, has made remarkable advances in recent years with improvements in deep learning architectures and new large scale datasets. Applied at scale, map perception could massively boost the applicable domains of automated driving.

A gap in research currently exists regarding logical consistency-aware training of these models. As seen in the image above, it is possible for a model to e.g. have a lane centerline that crosses with a road border, as this is never enforced in training. The aim of this thesis is to design logical consistency losses in this manner and apply them to state-of-the-art map perception deep learning architectures.

The proposed thesis consists of the following parts:

- + Literature research about Birds-Eye-View Road Feature Perception
- + Design of Logical Consistency Losses
- + Adaption of a dataset for the learning task, e.g. [3]
- + Implementation and training of a network
- + Evaluation of the resulting performance

References

- [1] Bencheng Liao et al. (2023). MapTRv2: An End-to-End Framework for Online Vectorized HD Map Construction.
- [2] Yi Zhou et al. (2024). HIMap: Hybrid Representation Learning for End-to-end Vectorized HD Map Construction.
- [3] Wilson, B., Qi, W., Agarwal, T., Lambert, J., Singh, J., Khandelwal, S., ... & Hays, J. (2023) Argoverse 2: Next generation datasets for self-driving perception and forecasting.

Additional Information

- + Students of other faculties than Mechanical Engineering are also welcome!
- + I am happy to answer any questions you might have. Feel free to ask for an appointment or directly ask at my office!

Institute of Measurement and Control Systems (MRT)
Prof. Dr.-Ing. Christoph Stiller

Advisor:

Fabian Immel, M.Sc.

Programming language(s)¹:

Python proficient

System, Framework(s):

Pytorch/Numpy, Linux

Required skills:

- Prior knowledge of deep learning / neural networks
- Experience with numerical libraries in Python like Numpy or Pytorch
- Work on your own

What we offer:

- Technical guidance by experienced deep learning practitioners
- Work on state of the art research
- Access to large scale GPU resources for model training

Language(s):

German, English

For more information please contact:

Fabian Immel

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Phone: +49 721 9654-263

Email: fabian.immel@kit.edu

Or directly send in your application including your current grades and a brief description of your prior coding experience!

¹ skill levels:

beginner < 500 lines of code (LOC)

advanced 500 – 5000 LOC

proficient > 5000 LOC